

Today

→ Resource-constrained ML  
Motivation

→ Decision trees

→ Bonsai

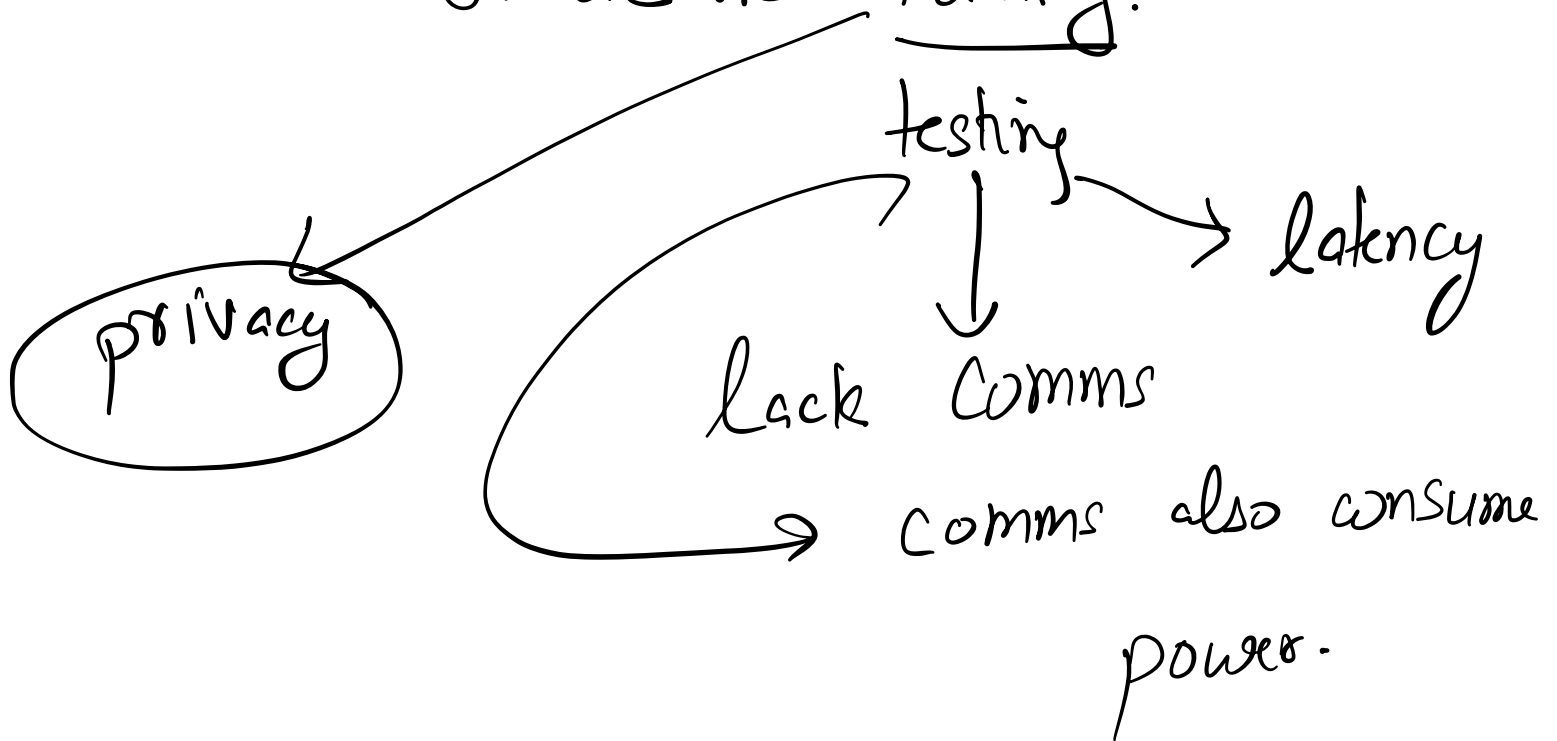
→ Design

→ Training

→ Results.

# Resource Constrained ML

Q. Why do we want to run on-device training?



Arduino Uno

2 kB SRAM

16 MHz

32 kB flash

1000

AlexNet

$10^7 - 10^8$   
4 bits

parameters

400 Mb of data

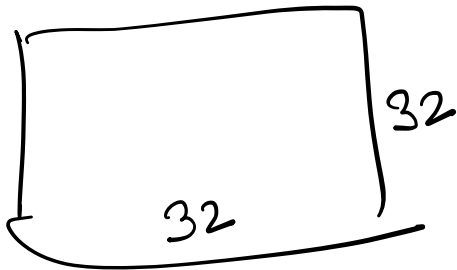
→ 50 MB

BBC Micro:bit

16 kB SRAM

16 MHz processor

256 kB flash



$$32 \times 32 \times 3 \times 4$$

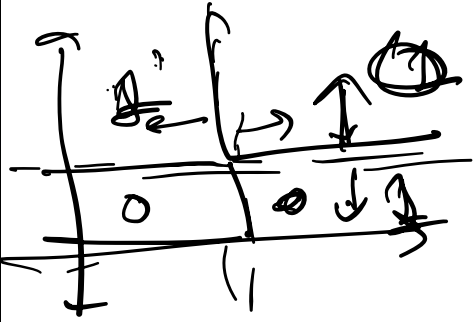
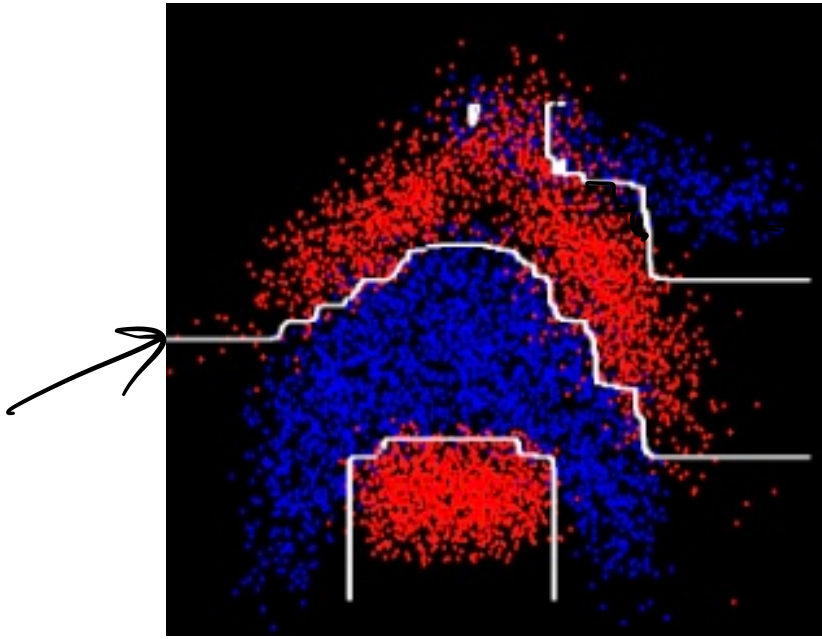
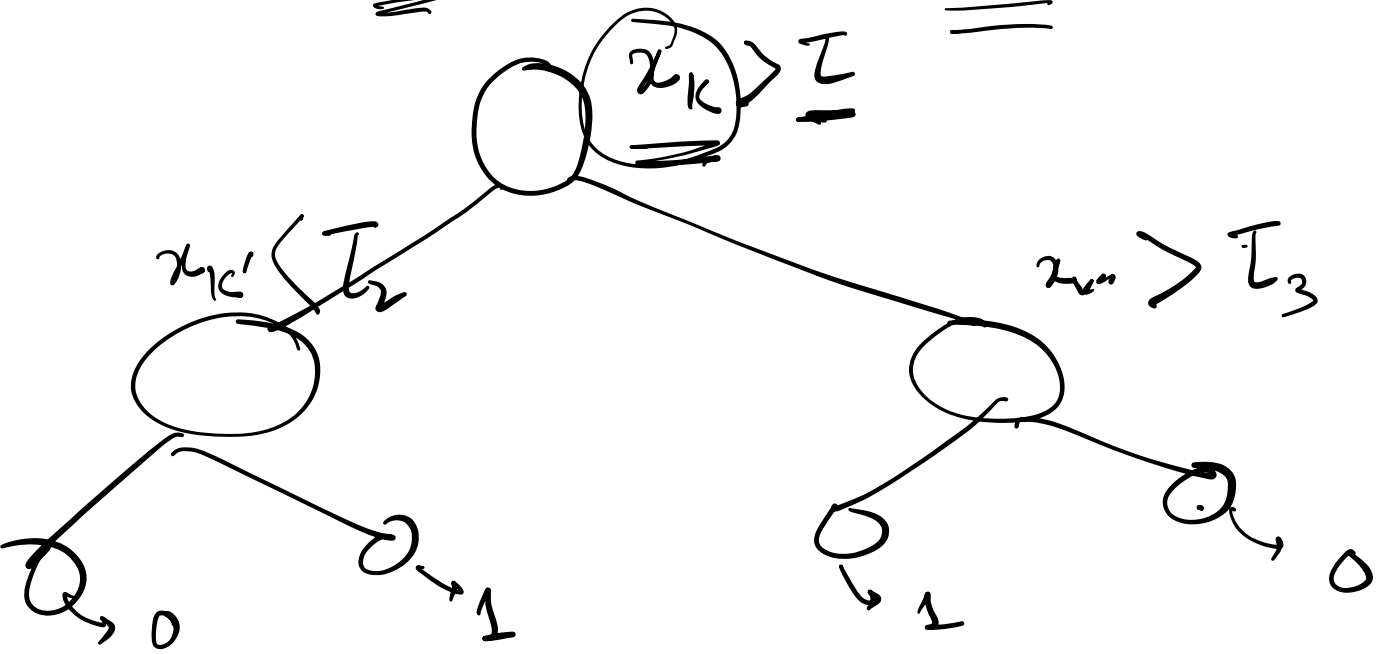
$$2^5 \times 2^5 \times 2^2 \times 3$$

$$12 \times 10^3$$

12 kB

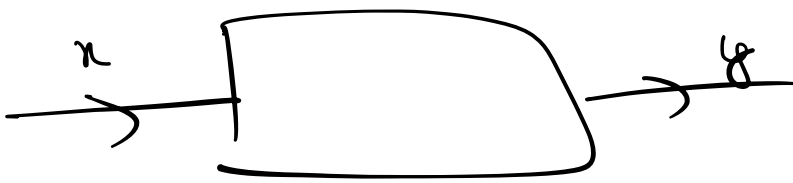
# Decision Trees

$[ \underline{x_0}, \dots, \underline{x_k}, \dots, \underline{x_N} ]$



# Bonsai: Key Ideas

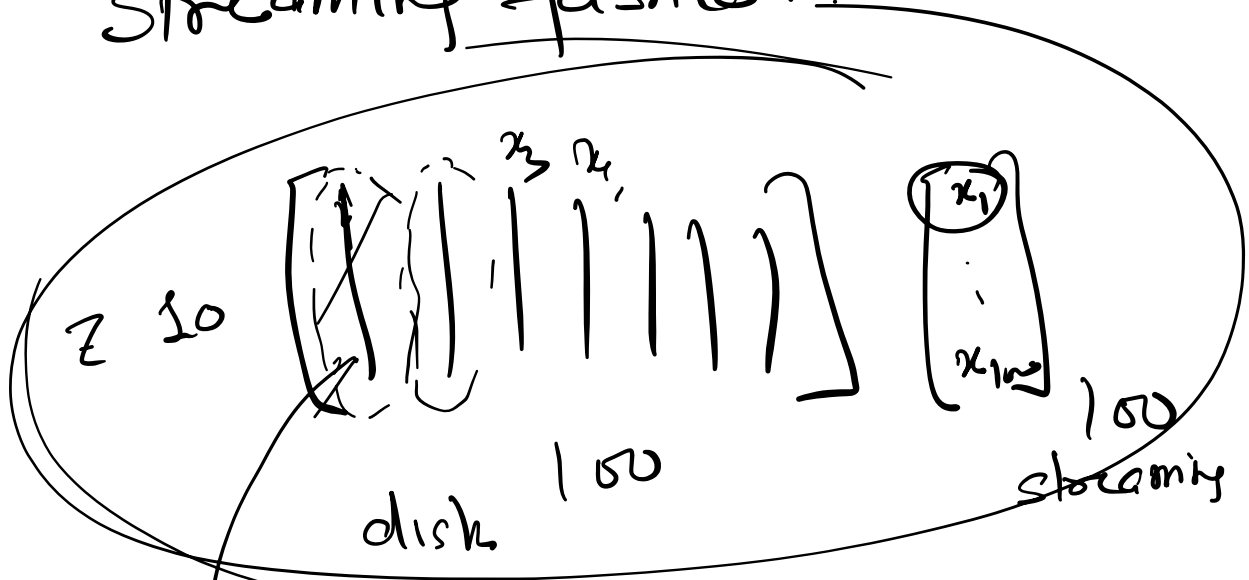
$$y(\mathbf{x}) = \sum_k I_k(\mathbf{x}) \mathbf{W}_k^T \mathbf{Z} \mathbf{x} \circ \tanh(\sigma \mathbf{V}_k^T \mathbf{Z} \mathbf{x})$$



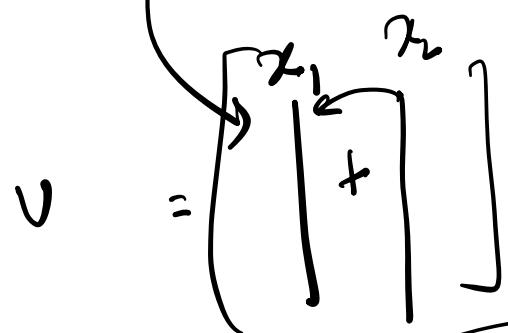
projection matrix.

don't have enough memory  $\Rightarrow$  project  $x \Rightarrow z x$   
 $(d) \quad d' \ll d$

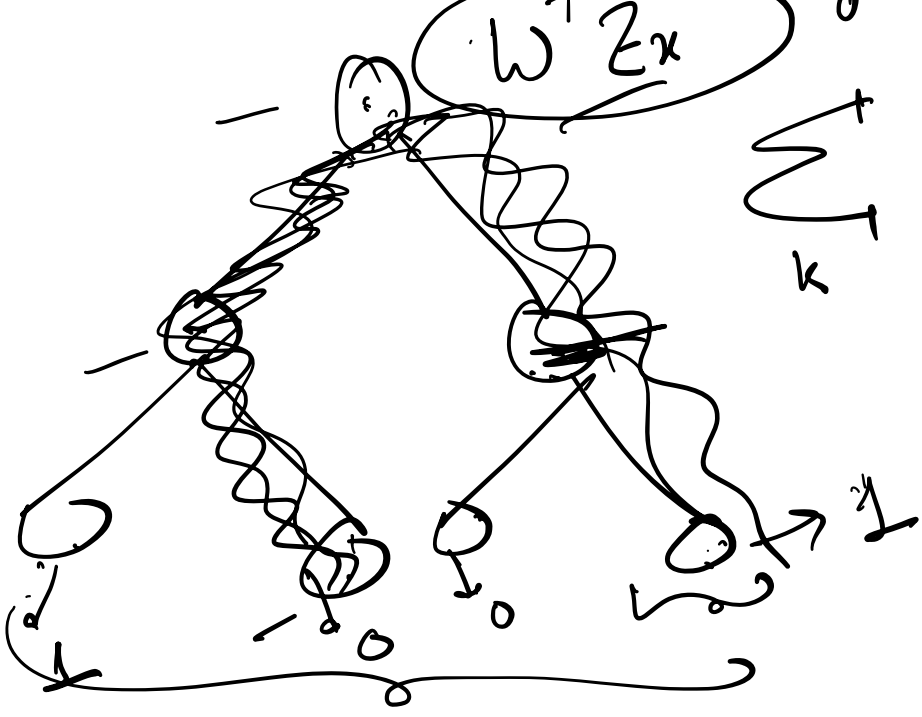
## Streaming fashion



streaming from the sensor.



$$\tanh(\sigma \mathbf{V}^T \mathbf{z} \mathbf{x})$$



$$\sum_k I_k$$

$k \in \text{path} \Rightarrow I_k = 1$   
 $k \notin \text{path} \Rightarrow I_k = 0$

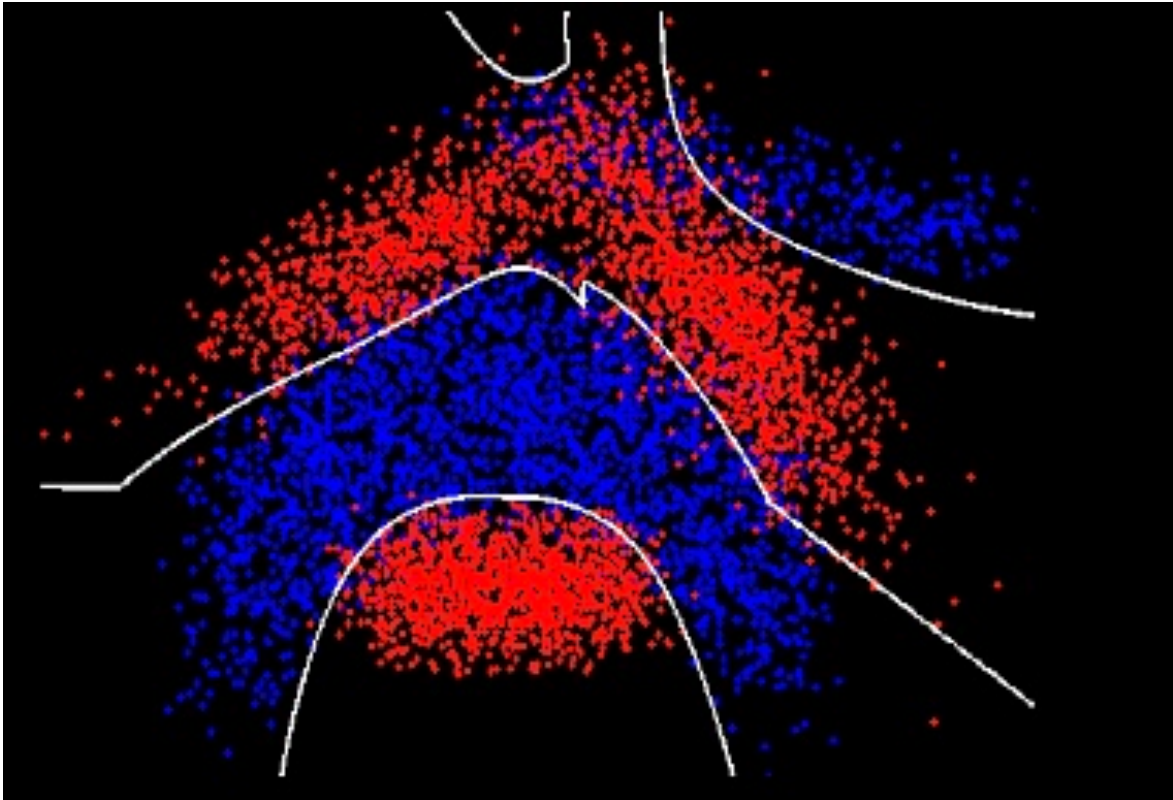
7 input functions  $\rightarrow$  3 functions per input  
 12 functions  $\rightarrow$  3 functions per input

tanh  $\rightarrow$  non-linearity in deep nets.

$$I_k(x) = \frac{1}{2} \left( 1 + \frac{(-1)^{k-2j}}{\tanh\left(\frac{\theta^T z_x}{2}\right)} \right)$$

$\theta^T z_x > \alpha$   
 $x_i > \alpha / I$

$\theta_j^T z_x$



Sparse Streaming



# Loss Functions

$$\min_{\mathbf{Z}, \Theta} \mathcal{J}(\mathbf{Z}, \Theta) = \frac{\lambda_{\theta}}{2} \text{Tr}(\Theta^{\top} \Theta) + \frac{\lambda_{\mathbf{W}}}{2} \text{Tr}(\mathbf{W}^{\top} \mathbf{W})$$
$$+ \frac{\lambda_{\mathbf{V}}}{2} \text{Tr}(\mathbf{V}^{\top} \mathbf{V}) + \frac{\lambda_{\mathbf{Z}}}{2} \text{Tr}(\mathbf{Z} \mathbf{Z}^{\top})$$
$$+ \frac{1}{N} \sum_{i=1}^N \mathcal{L}(\mathbf{x}_i, \mathbf{y}_i, \mathbf{y}(\mathbf{x}_i); \mathbf{Z}, \Theta)$$

$$\text{s. t. } \|\mathbf{Z}\|_0 \leq B_{\mathbf{Z}}, \|\Theta\|_0 \leq B_{\Theta}$$

$$\mathcal{H} \in \mathcal{L}(\Theta, \omega, \nu)$$

pruning

zero out the smallest values.

optimization

pruning



# Training Process

Gradient-based update step

$$\begin{aligned} \mathbf{Z}^{t+1} &= \mathbf{Z}^t - \eta_{\mathbf{Z}}^t \nabla_{\mathbf{Z}} \mathcal{J}(\mathbf{Z}^t, \Theta^t) \Big|_{\text{supp}(\mathbf{Z}^t)} \\ \Theta^{t+1} &= \Theta^t - \eta_{\Theta}^t \nabla_{\Theta} \mathcal{J}(\mathbf{Z}^t, \Theta^t) \Big|_{\text{supp}(\Theta^t)} \end{aligned}$$

} M steps

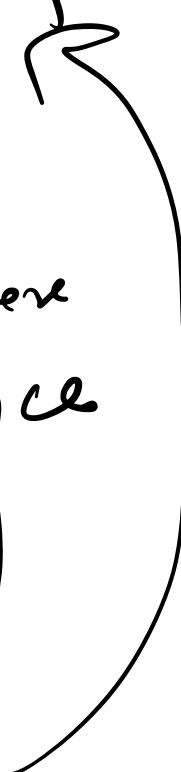


Update gradient everywhere once

↓ pruning

---


$$\begin{aligned} \mathbf{Z}^{t+M+1} &= \mathbf{T}_{B_{\mathbf{Z}}}(\mathbf{Z}^{t+M} - \eta_{\mathbf{Z}}^{t+M} \nabla_{\mathbf{Z}} \mathcal{J}(\mathbf{Z}^{t+M}, \Theta^{t+M})) \\ \Theta^{t+M+1} &= \mathbf{T}_{B_{\Theta}}(\Theta^{t+M} - \eta_{\Theta}^{t+M} \nabla_{\Theta} \mathcal{J}(\mathbf{Z}^{t+M}, \Theta^{t+M})) \end{aligned}$$

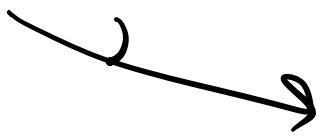


B<sub>Z</sub>

↳ 10 KB

B (H)

10000, 1B

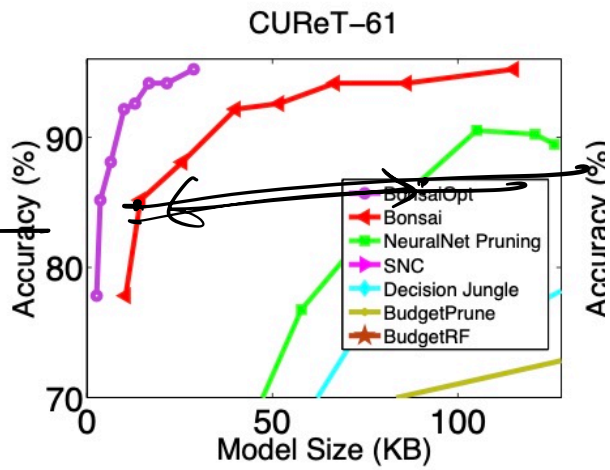
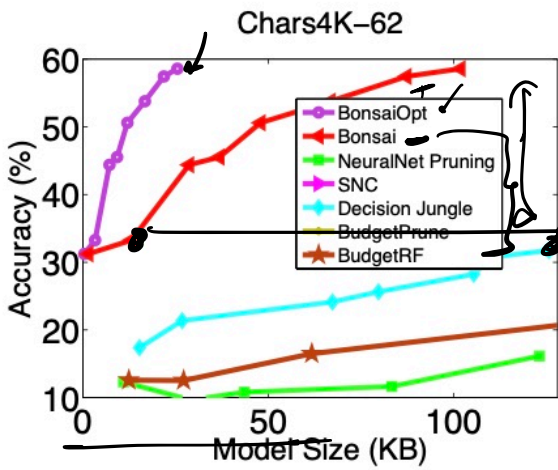


20000, 4bits

red.

# Experiments

TinyML



Dataset		BonsaiOpt	Bonsai	Linear	LDKL	NeuralNet Pruning	Cloud GBDT
Eye-2	Model Size (KB)	0.30	1.20	2.00	1.88	1.96	586.00
	Accuracy (%)	88.78	88.26	80.10	66.33	80.45	84.18
	Prediction Time (ms)	10.75	12.26	15.13	15.80	15.48	2186.59
	Prediction Energy (mJ)	2.64	3.01	3.72	3.89	3.81	1311.95
RTWhale-2	Model Size (KB)	0.33	1.32	0.86	1.00	1.17	156.00
	Accuracy (%)	60.94	61.74	50.76	50.24	52.44	59.40
	Prediction Time (ms)	5.24	7.11	4.68	6.16	8.86	521.27
	Prediction Energy (mJ)	1.29	1.75	1.15	1.52	2.18	312.76
Chars4K-2	Model Size (KB)	0.50	2.00	1.56	1.95	1.96	125.00
	Accuracy (%)	74.71	74.28	51.06	67.29	63.90	73.49
	Prediction Time (ms)	4.21	8.55	7.39	8.61	14.09	160.40
	Prediction Energy (mJ)	1.03	2.10	1.81	2.13	3.48	63.52
WARD-2	Model Size (KB)	0.47	1.86	1.99	1.99	1.91	93.75
	Accuracy (%)	95.70	95.86	87.57	89.64	91.76	98.05
	Prediction Time (ms)	4.85	8.13	7.48	9.99	14.22	293.13
	Prediction Energy (mJ)	1.18	1.99	1.84	2.47	3.49	116.08
CIFAR10-2	Model Size (KB)	0.50	1.98	1.56	1.88	1.96	625.00
	Accuracy (%)	73.05	73.02	69.11	67.54	67.01	76.68
	Prediction Time (ms)	4.55	8.16	7.73	8.12	13.87	160.40
	Prediction Energy (mJ)	1.11	2.01	1.90	2.00	3.43	63.52
USPS-2	Model Size (KB)	0.50	2.00	1.02	1.87	2.00	468.75
	Accuracy (%)	94.42	94.42	83.11	91.96	88.68	96.11
	Prediction Time (ms)	2.93	5.57	4.15	5.59	9.51	83.45
	Prediction Energy (mJ)	0.71	1.37	1.02	1.37	2.33	33.05
MNIST-2	Model Size (KB)	0.49	1.96	1.93	1.87	1.90	93.75
	Accuracy (%)	94.28	94.38	86.16	87.01	88.65	98.24
	Prediction Time (ms)	5.17	8.90	6.72	8.72	14.67	264.96
	Prediction Energy (mJ)	1.27	2.18	1.65	2.16	3.59	104.92

→ Chars4K-2  
 400  
 → WARD-2  
 1000  
 x 2  
 → CIFAR10-2  
 400  
 → USPS-2  
 250  
 → MNIST-2  
 784  
 x 2

9.520  
 MIT